

Document made available under the Patent Cooperation Treaty (PCT)

International application number: PCT/GB05/001036

International filing date: 18 March 2005 (18.03.2005)

Document type: Certified copy of priority document

Document details: Country/Office: GB
Number: 0406278.2
Filing date: 19 March 2004 (19.03.2004)

Date of receipt at the International Bureau: 26 May 2005 (26.05.2005)

Remark: Priority document submitted or transmitted to the International Bureau in compliance with Rule 17.1(a) or (b)



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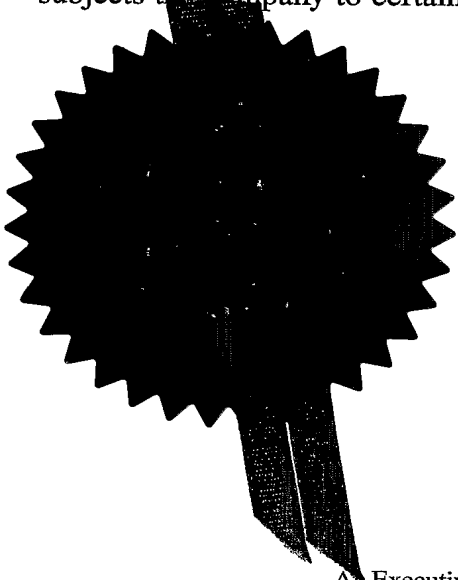
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19 MAR 2004

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Patents ADP number (if you know it)

449769004

If the applicant is a corporate body, give the country/state of its incorporation

United Kingdom

4. Title of the invention

Fuel Level Sensor

5. Name of your agent (if you have one)

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Description 6

Claim(s) 2

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D Young & Co

Date 19 March 2004

12. Name, daytime telephone number and e-mail address, if any, of person to contact in the United Kingdom

D Young & Co (Agents for the Applicants)

Richard Pratt

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Fuel Level Sensor

The present invention relates to a fuel level sensor.

US-A-6593734, the disclosure of which is incorporated herein, discloses a
5 magnetic position sensor having a stator and a movable part. The stator has two soft
magnetic pieces defining an air gap which contains a magnetosensitive probe, for
example a Hall effect sensor, for measuring the variation in induction in the gap. The
moveable part comprises a yoke of soft magnetic material displaceable parallel to the
magnetic pieces of the stator and a magnet partly embedded in the yoke. The magnet's
10 poles are parallel to the pieces of the stator. Movement of the magnet relative to the
stator varies the magnetic field in the air gap and the magnetosensitive probe produces
a signal representing the position of the magnet relative to the stator.

Most fuel level sensors, currently in use, use a float connected by a pivoted arm
to a conductive wiper which moves along an electrically resistive strip. This causes the
15 resistance of the sensor to change with the movement of the wiper. The change in
current through the strip indicates variations in fuel level. These sensors operate inside
the fuel tank, often attached to an assembly containing the fuel pump. The wiper and
resistive strip are exposed to the fuel. The fuel level sensor is expected to operate
reliably for a long period of time. However, the strip is continually rubbed by the
20 wiper, some fuels are corrosive, and it has been found that cleaner fuels aggravate
wear. Also, to keep the contact of the wiper clean and to burn off films deposited by
the fuel on the sensor, an operating current of tens of milliamps is often used.

The present invention provides a fuel level sensor having a magnetic position
sensor connected to an arm for attachment to a float, wherein the magnetic position
25 sensor comprises a stator and a movable part, the stator having two soft magnetic
pieces defining an air gap which contains a magnetosensitive probe for measuring the
variation in induction in the gap, the moveable part comprises a yoke of soft magnetic
material displaceable parallel to the magnetic pieces of the stator and a magnet joined
to the yoke, the poles of the magnet being polarised perpendicularly to the direction of
30 movement of the moveable part relative to the stator.

Suitably, the magnet's poles are parallel to the pieces of the stator. Movement of the magnet relative to the stator varies the magnetic field in the air gap and the magnetosensitive probe produces a signal representing the position of the magnet relative to the stator.

5 Suitably, the magnet is partly embedded in a cavity in the yoke.

Such a magnetic position sensor has a stator and moveable part which do not contact each other thus avoiding wear due to rubbing of two parts. The use of a magnetic sensor having a magnetosensitive probe, for example a Hall effect sensor, reduces the current consumption. The current consumption is further reduced because
10 there is no need to provide a current to burn off films deposited by the fuel or to keep wiper contacts clean.

Fuel level sensors are often positioned in close proximity to the fuel pump to facilitate assembly in the fuel tank. It is a feature of the present invention that it provides robust immunity to magnetic fields caused either by pump motor magnetic
15 fields or proximity to of ferrous casings or supports. These fields may influence other sensing techniques, for instance those which rely on magnetic flux orientation detection more readily and can require additional magnetic shielding.

In an embodiment, the magnetosensitive probe is Hall effect sensor. In a currently preferred embodiment, the Hall effect sensor is part of an Integrated Circuit
20 (IC) also having an arithmetic circuit and some memory.

The IC may be pre-programmed to set minimum and maximum outputs to reduce mechanical errors.

In an embodiment, the IC has two power leads which also act a signalling leads to indicate the fuel level. The IC converts the position signal from the magnetic
25 position sensor to a binary, Pulse Code Modulated, signal which is a modulation of power supply current, for example 5mA for one level and 10mA for the other.

Modern vehicles have at least one computer for instruments and engine management. In an embodiment of the invention, the vehicle's computer converts the fuel level signal from the fuel level sensor to an instrument reading taking account of
30 the shape of the fuel tank. Alternatively, the IC, of which the Hall sensor forms part, may include a means for calibrating the output of the fuel level sensor to suit the shape of a fuel tank. Such means may be a programmable device, for example a look up

table, which can be programmed according the shape of any fuel tank. Thus any need to design different sensors for different fuel tanks (apart from programming) may be avoided.

5 The IC may also provide other information, for example fault indication and/or part identification. The IC may also provide other signal processing, for example temperature compensation.

For a better understanding of the present invention, reference will now be made, by way of example, to the accompanying drawings in which:

Figure 1 is a schematic view of a magnetic position sensor;

10 Figure 2 is a schematic view of a fuel level sensor incorporating a sensor as shown in Figure 1; and

Figure 3, is a block diagram of the fuel level sensor of Figure 2.

The sensor of Figure 1 is provided with a fixed stator (1) and a part (2) which is movable in the direction OX, with a useful stroke X_c over which the delivered signal
15 has great linearity.

The stator is provided with two stator pieces (3, 4) of a soft magnetic material in the form of annular quadrants. Movable part (2) has a soft iron yoke (5) of semiannular form. Stator pieces (3, 4) and yoke (5) define between them a primary air gap (7). Yoke (5) has a cavity (6) in which there is housed a magnet (8) magnetized
20 perpendicular to air gap (7), or in radial direction in the present case.

The stator has two ferromagnetic pieces (3, 4) spaced apart by a secondary air gap (9) of length F, in which there is placed a magneto-sensitive probe (10). The two stator pieces (3, 4) are joined by nonmagnetic pieces made of brass, for example, and are aligned in the same cylindrical surface, whose axis is the axis of rotation of the
25 movable part.

The stroke X_c is the width of the angular arc travelled by the movable part over the mean radius R_m of the magnetized part. The stroke of the magnet extends by $\pm X_c/2$ relative to the center of the secondary air gap, in which the magneto-sensitive probe is disposed perpendicular to the primary air gap.

30 The movable part (2) is provided with a yoke (5) of soft magnetic material and a permanent magnet (8) partly embedded in yoke (5). Magnet (8) is polarized radially,

or in other words perpendicular to OX. Movable part (2) is displaced parallel to stator pieces (3, 4) at a constant minimal distance Y_0 measured perpendicular to OX.

Permanent magnet (8) is partly embedded in a cavity situated substantially at the center of movable yoke (5), on the side of stator pieces (3, 4), at a depth e such that
5 $0.1 L < e < 0.9 L$, where L is the thickness of magnet (8) in the polarization direction. Depth e is determined in such a manner as to optimize the characteristics of the sensor.

Permanent magnet (8) is displaced together with yoke (5) parallel to stator pieces (3, 4) at a constant minimum distance $E-L$, where E is the distance between the stator pieces and the cavity bottom, measured perpendicular to OX. Yoke (5) is
10 situated at a minimum distance from the stator equal to $Y_0 = E - e$, which is larger than $E-L$.

Width X_s of stator pieces (3, 4) measured over the mean radius R_m of magnet (8) is greater than or equal to X_c , preferably substantially equal to $X_c + 2 E'$, in order to obtain a signal with great linearity over the entire stroke X_c , where E' ranges between
15 $e/4$ and E .

Preferably the width of the cavity in movable yoke (5) and of magnet (8), measured over the mean radius R_m of magnet (8), is larger than or equal to $X_c + F$, preferably substantially equal to $X_c + F + 2 E'$.

According to an advantageous modification, the width of movable yoke (5) measured over the mean radius R_m of magnet (8) is equal to at least $3 X_c + F + 6 E'$.
20

According to an advantageous modification, the L/E ratio is greater than or equal to 0.5, and preferably greater than or equal to 0.75.

According to an advantageous modification, the X_s/E ratio is relatively large, preferably greater than 8.

25 According to an advantageous modification, magnet (8), movable yoke (5) and ferromagnetic stator pieces (3, 4) have the same length Z measured along the axis perpendicular to the direction of magnetization and to the direction of displacement OX, and preferably greater than or equal to $3 E$.

These advantageous modifications make it possible to define a sensor with an
30 optimal geometry and volume of magnet (8) adapted to the desired measurement range.

Magneto-sensitive probe (10) can be a Hall-effect probe, a magneto-resistive probe, a magnetic transistor, etc. What is important is that the delivered signal depends as linearly as possible on the magnetic induction in which this element is placed.

5 Permanent magnet (8) can be of different types, and preferably there will be used a magnet (8) of samarium-cobalt or NdFeB, or possibly even a magnet (8) of AlNiCo or ferrite type, etc. It has a reversible permeability close to 1, and preferably less than 1.2, in order to obtain good linearity of the signal. It will be preferable to choose a magnet (8) with a low temperature coefficient.

10 The ferromagnetic stator parts and movable yoke (5) can be made of iron-nickel, iron-silicon, pure iron, etc.

It is not necessary to introduce a guide piece for magnet (8), since it is directly fixed on movable yoke (5). The embedding of magnet (8) in yoke (5) also makes it possible to reduce the sensitivity of the sensor to the quality of bonding of magnet (8), and it facilitates placement of the magnet on yoke (5) during production operations.

15 It is possible to minimize the volume of magnet (8) or to increase the induction variation ΔB and thus the signal-to-noise ratio.

The depth e of the cavity provided in movable yoke (5) is chosen judiciously in order to increase, relative to the case without cavity ($e=0$), with an identical magnet (8) and the same overall outside dimensions, the magnetic induction delivered by the magnetic circuit to magneto-sensitive probe (10), and/or in order to improve the linearity of the sensor along the stroke.

20 The embedding of permanent magnet (8) modifies the distribution and amplitude of leakage fluxes, and thus makes it possible to influence the linearity of the sensor. It can be shown that the linearity varies as a function of the depth of cavity (6) in which permanent magnet (8) is partly embedded.

Referring to Figure 2, the fuel level sensor 42 comprises a base frame 40 which may be a plastics moulding. The base frame 40 supports the stator 1 comprising the pole pieces 3,4 defining the air gap 9 in which is the Hall effect sensor 10. The base frame 40 also supports a lead frame 14 of electrical connectors connecting to the Hall effect sensor. The yoke 5 has the magnet 8 partly embedded in the cavity 6. The yoke

pivots on a bearing 41. The yoke is connected to an arm 12 for attachment to a float (not shown).

Referring to Figure 3, the fuel level sensor 42 comprises the Hall effect sensor 16 which is connected to an analogue to digital (A/D) converter 18. The output of the A/D converter is connected to a signal processor 20 which is for example a digital processor including an arithmetic circuit and memory M, 22. The output of the processor is connected to a Pulse Code Modulator 24 which binary modulates the current flowing in power supply leads 28 connected to terminals T. The binary symbols may be currents of 5mA and 10mA for example, although any other suitable values may be used. A power supply 26 supplies DC to the elements 16, 18, 20 and 24 unaffected by the modulation of the current in the leads 28.

In a preferred example of Figure 3 the Hall effect sensor 9 is part of an IC also comprising the A/D converter 18 and the processor 20, and optionally also the modulator 24.

The memory 22 may store a look up table LUT for calibrating the output of the Hall effect sensor with the shape of the fuel tank. The processor 20 addresses the LUT in accordance with the output of the Hall sensor 16 reads out values which, for example, are linearly related to the volume of fuel in the tank regardless of the shape of the tank.

Alternatively, a vehicle may have a computer for operating the vehicle instruments including the fuel gauge, and which stores such a look up table and the processor supplies to the computer via the modulator 24 the "raw" output of the Hall sensor.

The processor 20 may provide other functions for example one or more of: fault indication; part identification; and temperature compensation.

The fuel level sensor 42 may be part of a fuel pump.

Whilst the example of Figure 3 uses digital signal processing, another example of the fuel level sensor provides an analogue signal representing fuel level.

CLAIMS

1. A fuel level sensor having a magnetic position sensor connected to an arm for attachment to a float, wherein the magnetic position sensor comprises a stator and a movable part, the stator having two soft magnetic pieces defining an air gap which contains a magnetosensitive probe for measuring the variation in induction in the gap, the moveable part comprising a yoke of soft magnetic material displaceable parallel to the magnetic pieces of the stator, and a magnet partly embedded in a cavity in the yoke facing the stator, the poles of the magnet being polarized perpendicularly to direction of movement of the moveable part relative to the stator.
2. A sensor according to claim 1, wherein the magnetosensitive probe is a Hall effect sensor.
3. A sensor according to claim 2, further comprising a signal processor for processing a signal produced by the magnetic position sensor and representing the position of the moveable part relative to the stator.
4. A sensor according to claim 3, wherein the signal processor and the magnetosensitive probe are parts of the same integrated circuit.
5. A sensor according to claim 3, or 4, wherein the sensor has two power terminals and the signal processor is operable to output the signal representing the position of the moveable part relative to the stator on the power terminals.
6. A sensor according to claim 5 wherein the said signal is a Pulse Code Modulated signal.
7. A sensor according to claim 3, 4, 5, or 6, wherein the signal processor is operable to provide fault indication and/or part identification.
8. A sensor according to claim 3, 4, 5, 6, or 7, wherein the signal processor is operable to provide temperature compensation.
9. A sensor according to any preceding claim in combination with a fuel pump.

10. A sensor according to any one of claims 3 to 9, wherein the signal processor is programmable to calibrate the output of the sensor to the shape of a fuel tank.
11. A vehicle comprising a sensor according to any preceding claim.
- 5 12. A vehicle comprising a computer and a sensor according to any one of claims 1 to 10, wherein the said computer is arranged to calibrate the output of the sensor to the shape of a fuel tank of the vehicle.
13. A sensor substantially as hereinbefore described with reference to the accompanying drawings.
- 10 14. A vehicle comprising a sensor according to claim 13.

ABSTRACT

FUEL LEVEL SENSOR

A fuel level sensor comprises a magnetic position sensor attached to an arm for carrying a float.

5

[Figure 2]



Exploded perspective view of a magnetic disk drive assembly. The components are labeled with numbers 1 through 14:

- 1: Rotating disk
- 2: Rotating float arm
- 3: Pole piece
- 4: Edge piece
- 5, 6, 8: (Grouped label for components 5, 6, and 8)
- 9: Lead frame for sensor cable connections
- 10: Base frame
- 11: (Unlabeled component, likely a disk cover or spacer)
- 12: Rotating float arm (labeled again)
- 13: (Unlabeled component, likely a disk cover or spacer)
- 14: Lead frame for sensor cable connections (labeled again)

Figure 2.

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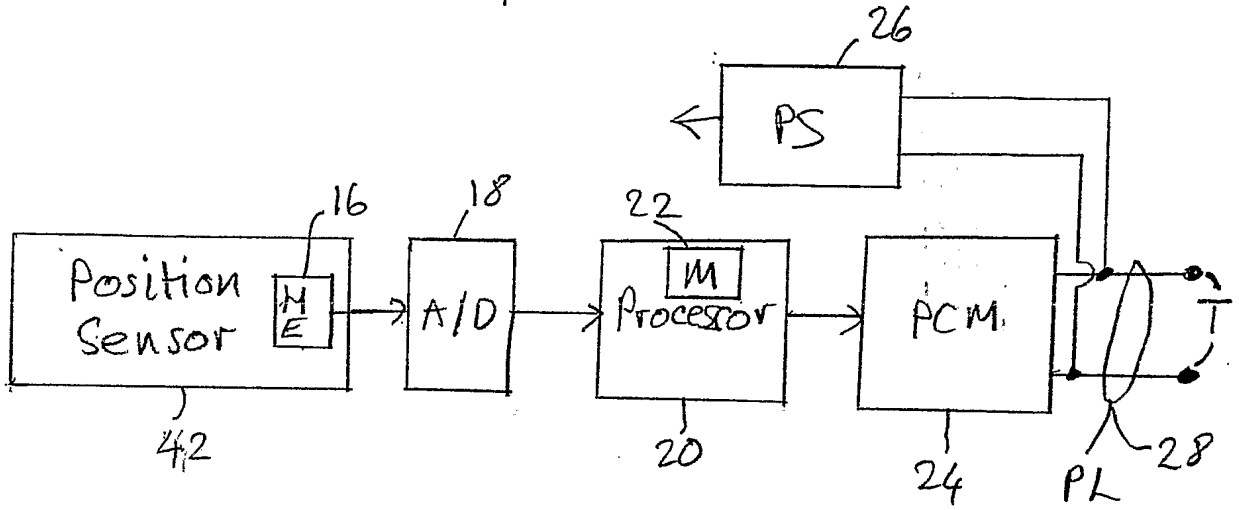


Figure 3.

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